# **Parallel programming / computation**

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IITU

# Lecture 1 MPI Overview

- 1. MPI Overview
  - one program on several processors
  - work and data distribution



- 2. Process model and language bindings
  - starting several MPI processes

MPI\_Init() MPI\_Comm\_rank()

- 3. Messages and point-to-point communication
  - the MPI processes can communicate
- 4. Nonblocking communication
  - to avoid idle time, deadlocks and serializations



- 5. The New Fortran Module mpi\_f08
- 6. Collective communication
  - (1) e.g., broadcast
  - (2) e.g., nonblocking collectives, neighborhood communic.
- 7. Error handling

MPI Outline

Handout is

sorted by content ...

- error handler, codes, and classes

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(; •••i•i)

- 8. Groups & Communicators, Environmental Management
  - (1) MPI\_Comm\_split, intra- & inter-communicators
  - (2) Re-numbering on a cluster, collective communication on inter-communicators, info object, naming & attribute caching, implementation information, Sessions Model
- 9. Virtual topologies

   (1) A multi-dimensional process naming scheme
   (2) Neighborhood communication + MPI\_BOTTOM
   (3) Optimization through reordering

... whereas **course** is sorted by **beginners /** intermediate / advanced

- 10. One-sided Communication
  - Windows, remote memory access (RMA)
  - Synchronization



- 11. Shared Memory One-sided Communication
  - (1) MPI\_Comm\_split\_type & MPI\_Win\_allocate\_shared Hybrid MPI and MPI shared memory programming
  - (2) MPI memory models and synchronization rules
- 12. Derived datatypes



- (1) transfer any combination of typed data
- (2) advanced features, alignment, resizing
- 13. Parallel File I/O
  - (1) Writing and reading a file in parallel
  - (2) Fileviews
  - (3) Shared Filepointers, Collective I/O ...
- 14. MPI and Threads
  - e.g., hybrid MPI and OpenMP, partitioned point-to-point communication



MPI Outline

- 15. Probe, Persistent Requests, Cancel
- 16. Process Creation and Management
  - Spawning additional processes
  - Singleton MPI\_INIT
  - Connecting two independent sets of MPI processes
- 17. Other MPI features [1, 2, 13.1-3, 15, 16-18, 19.3, A, A.2, B]
- 18. Best practice
  - Parallelization strategies (e.g. Foster's Design Methodology)
  - Performance considerations
  - Pitfalls and progress / weak local
- 19. Heat example

Summary

Appendix



# **Information about MPI**

- MPI: A Message-Passing Interface Standard, Version 4.0 (June 9, 2021) (pdf & printed hardcover book [MPI-3.1 only] → online via www.mpi-forum.org)
- Marc Snir and William Gropp et al.: MPI: The Complete Reference, 1998. (outdated)
- William Gropp, Ewing Lusk and Anthony Skjellum: Using MPI: Portable Parallel Programming With the Message-Passing Interface. MIT Press, 3<sup>rd</sup> edition, Nov. 2014 (336 pages, ISBN 9780262527392), and William Gropp, Torsten Hoefler, Rajeev Thakur and Ewing Lusk: Using Advanced MPI: Modern Features of the Message-Passing Interface. MIT Press, Nov. 2014 (392 pages, ISBN 9780262527637).
- Peter S. Pacheco: **Parallel Programming with MPI**. Morgan Kaufmann Publishers, 1997 (very good introduction, can be used as accompanying text for MPI lectures).
- Neil MacDonald, Elspeth Minty, Joel Malard, Tim Harding, Simon Brown, Mario Antonioletti: Parallel Programming with MPI. Historical MPI course notes from EPCC. http://www.archer.ac.uk/training/course-material/2014/10/MPI\_UCL/Notes/MPP-notes.pdf
- All MPI standard documents and errata via www.mpi-forum.org
- http://en.wikipedia.org/wiki/Message\_Passing\_Interface (English)
   http://de.wikipedia.org/wiki/Message\_Passing\_Interface (German)
- Tools: see VI-HPS (Virtual Institute High Productivity Supercomputing) <u>https://www.vi-hps.org/</u> Tools Guide: <u>https://www.vi-hps.org/cms/upload/material/general/ToolsGuide.pdf</u> & <u>training events</u>
- **Python:** See <u>MPI for Python (mpi4py.github.io)</u>, and <u>MPI for Python documentation</u> (mpi4py.readthedocs.io), and the <u>Reference (mpi4py.readthedocs.io/en/stable/reference.html)</u>

Outdated API reference: mpi4py.github.io/apiref/index.html

# The Message-Passing Programming Paradigm

Sequential Programming Paradigm



# The Message-Passing Programming Paradigm

Sequential Programming Paradigm



Message-Passing Programming Paradigm



# **Analogy: Electric Installations in Parallel**

- MPI sub-program

   work of one electrician
   on one floor
- MPI process on a dedicated hardware
   = the electrician
- data
   the electric installation
- MPI communication

   real communication
   to guarantee that the wires
   are coming at the same
   position through the floor



shared memory



## Socket/CPU

•••

→ memory interface

UMA (uniform memory access) SMP (symmetric multi-processing) All cores connected to all memory banks with same speed

#### Parallel execution streams on each

core, e.g., x[ 0 ... 999] = ... on 1<sup>st</sup> core x[1000 ... 1999] = ... on 2<sup>nd</sup> core x[2000 ... 2999] = ... on 3<sup>rd</sup> core

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## Node

→ hyper-transport

#### ccNUMA (cache-coherent non-uniform

#### memory access)

→ Shared memory programming is possible !! **#CPUs x memory bandwidth** !!

#### Performance problems:

- Each parallel execution stream should mainly access the memory of its CPU
   → First-touch strategy is needed to minimize remote memory access
- Threads should be pinned to the physical sockets

shared memory



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Shared memory programming with OpenMP

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Shared memory programming with OpenMP

# distributed memory



## Cluster

#### → node-interconnect

NUMA (non-uniform memory access) !! fast access only on its own memory !! Many programming options:

- Shared memory / symmetric multiprocessing inside of each node
- distributed memory parallelization on the node interconnect
- Or simply one MPI process on each core

### shared memory



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Shared memory programming with OpenMP

MPI works everywhere

# The Message-Passing Programming Paradigm

- Each processor in a message passing program runs a *sub-program:* 
  - written in a conventional sequential language, e.g., C, Fortran, or Python
  - typically the same on each processor (SPMD),
  - the variables of each sub-program have
    - the same name
    - but different locations (distributed memory) and different data!
    - i.e., all variables are private
  - communicate via special send & receive routines (*message passing*)



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# **Data and Work Distribution**

- the value of *myrank* is returned by special library routine
- the system of *size* processes is started by special MPI initialization program (mpirun or mpiexec)
- all distribution decisions are based on *myrank*
- i.e., which process works on which data



# What is SPMD?

- Single Program, Multiple Data
- Same (sub-)program runs on each processor
- MPI allows also MPMD, i.e., Multiple Program, ...
- but some vendors may be restricted to SPMD
- MPMD can be emulated with SPMD

# **Emulation of Multiple Program (MPMD), Example**

```
• main(int argc, char **argv)
{
    if (myrank < .... /* process should run the ocean model */)
    {
        ocean( /* arguments */ );
    }else{
        weather( /* arguments */ );
    }
}</pre>
```

- PROGRAM
   IF (myrank < ... ) THEN !! process should run the ocean model CALL ocean ( some arguments )

   ELSE
   CALL weather ( some arguments )

   ENDIF END
- if (myrank < ....): # process should run the ocean model ocean( ... )
   else: weather( ... )

# **Emulation of Multiple Program (MPMD), Example**

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main(int argc, char **argv)
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 PROGRAM
 IF (myrank < ... ) THEN !! process should run the ocean model CALL ocean ( some arguments )

 ELSE
 CALL weather ( some arguments )

 ENDIF
 END



first-example.c



```
#include <stdio.h>
#include <mpi.h>
int main(int argc, char *argv[])
{
```

MPI\_Init(&argc, &argv);

#### MPI\_Finalize();



#inaluda Katdia h. firet avample a	
	<b>Compiled</b> , e.g., with: mpicc first-example.c
<pre>#include <mpi.h> int main(int argc, char *argv[]) </mpi.h></pre>	Started, e.g., with: mpiexec -n 4 ./a.out Then, this code is running 4 times in parallel !
{	

MPI\_Init(&argc, &argv);

#### MPI\_Finalize();

}





#### MPI\_Finalize();





#### MPI\_Finalize();





	Enter the number of elements (n): 100	input/output
MPI_Finalize();		
— MPI course → Chap. 1 Overview		Slide 17

M



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$\frac{-}{MPI \text{ course}} \rightarrow \text{Chap. 1 Overview}$		Slide 17



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<pre>IPI_Finalize();</pre>		_
MPI course → Chap. 1 Overview		Slide 17



Enter the number of elements (n): input/outpu	Jt
I am process 0 out of 4 handling the 0th part of n=100 elements, result=0.0 I am process 2 out of 4 handling the 2th part of n=100 elements, result=200 I am process 3 out of 4 handling the 3th part of n=100 elements, result=300	0.0
I am process 1 out of 4 handling the 1th part of n=100 elements, result=100	.0
Slide 17	

MPI\_Finalize();

MPI course → Chap. 1 Overview



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MPI course → Chap. 1 Overview	Slide 17





Slide 17

MPI\_Finalize();










#### **Exercise 1 – Solution + Questions**

mpif90 first-example 30.f90 mpirun –np 6 ./a.out Enter the number of elements (n): 100 I am process 0 out of 6 handling the 0th part of n= 100 elements, result= 0.00 I am process 1 out of 6 handling the 1th part of n= 100 elements, result= 100.00 I am process 2 out of 6 handling the 2th part of n= 100 elements, result= 200.00 I am process 3 out of 6 handling the 3th part of n= 100 elements, result= 300.00 I am process 4 out of 6 handling the 4th part of n= 100 elements, result= 400.00 I am process 5 out of 6 handling the 5th part of n= 100 elements, result= 500.00 I'm proc 0: My own result is 0.00 I'm proc 0: received result of process 1 is 100.00 I'm proc 0: received result of process 2 is 200.00 I'm proc 0: received result of process 3 is 300.00 I'm proc 0: received result of process 4 is 400.00 I'm proc 0: received result of process 5 is 500.00

#### **Exercise 1 – Solution + Questions**

mpif90 first-example\_30.f90

mpirun –np 6 ./a.out

Enter the number of elements (n): 100

# Normally, you'll never see this perfect output !

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### **Exercise 1 – Solution + Answers**

mpif90 first-example_30.f90	General rule:
mpirun –np 6 ./a.out	The output of each process
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I'm proc 0: received result of process	5 is 500.00

The output from different processes can be intermixed in any sequence! Most MPI libraries try to not intersect output lines ③

#### Access

- A sub-program needs to be connected to a message passing system
- A message passing system is similar to:
  - mail box
  - phone line
  - fax machine
  - etc.
- MPI:
  - sub-program must be linked with an MPI library
  - sub-program must use include file of this MPI library
  - the total program (i.e., all sub-programs of the program) must be started with the MPI startup tool

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#### Messages



- Messages are packets of data moving between sub-programs
- Necessary information for the message passing system:
  - sending process
  - source location
  - source data type
  - source data size

- receiving process
- destination location
- destination data type
- destination buffer size



#### Messages



- Messages are packets of data moving between sub-programs
- Necessary information for the message passing system:



# Addressing

- Messages need to have addresses to be sent to.
- Addresses are similar to:
  - mail addresses
  - phone number
  - fax number
  - etc.
- MPI: addresses are ranks of the MPI processes (sub-programs)

# Receiving

• All messages must be received.

### **Point-to-Point Communication**

- Simplest form of message passing.
- One process sends a message to another.
- Different types of point-to-point communication:
  - synchronous send
  - buffered = asynchronous send

### Synchronous Sends

- The sender gets an information that the message is received.
- Analogue to the beep or okay-sheet of a fax.



# **Buffered = Asynchronous Sends**

• Only know when the message has left.



# **Blocking Operations**

- Operations are activities, such as
  - sending (a message)
  - receiving (a message)
- Some operations may **block** until another process acts:
  - synchronous send operation **blocks until** receive is posted;
  - receive operation **blocks until** message was sent.
- Relates to the completion of an operation.
- Blocking subroutine returns only when the operation has completed.

# **Nonblocking Operations**

Nonblocking operations consist of:

- A nonblocking procedure call: it returns immediately and allows the sub-program to perform other work
- At some later time the sub-program must *test* or *wait* for the completion of the nonblocking operation



**Non-Blocking Operations (cont'd)** 



- All nonblocking procedures must have a matching wait (or test) procedure. (Some system or application resources can be freed only when the nonblocking operation is completed.)
- A <u>nonblocking procedure immediately followed by a matching wait</u> is equivalent to a <u>blocking procedure</u>.
- Nonblocking procedures are not the same as sequential subroutine calls:
  - the operation may continue while the application executes the next statements!

#### **Interrupt: Example & Exercise 2**

- Before we further go through the MPI chapter overview on
  - Collective Communication
  - Parallel file I/O
- Lets look at halo communication
- plus a short exercise 2

#### **Example: Domain decomposition – serial**

•  $x_{new}(i,j) = f(x_{old}(i-1,j), x_{old}(i,j), x_{old}(i+1,j), x_{old}(i,j-1), x_{old}(i,j+1))$ 



#### **Example: Domain decomposition – parallel**

•  $x_{new}(i,j) = f(x_{old}(i-1,j), x_{old}(i,j), x_{old}(i+1,j), x_{old}(i,j-1), x_{old}(i,j+1))$ 



#### **Example: Domain decomposition – parallel**

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parallel code:



parallel code:









#### **Example code**

ib\_global = 0; ie\_global=n-1; // global xold, xnew: arrays with n elements and indexes 0 .. n-1

```
for(....) / e.g. timesteps
{
```

```
numerical_func( xold, xnew, ib_global, ie_global);
tmp=xold; xold=xnew; xnew=tmp; // exchanging role of xold and xnew
}
```

#### Example code

ib\_global = 0; ie\_global=n-1; // global xold, xnew: arrays with n elements and indexes 0 .. n-1



Goal: Divide a given amount of mesh elements in one dimension into subdomains

- Given: The number of processes: num\_procs (e.g., 4, i.e., 4 subdomains)
  - The number of mesh elements: n (e.g., **17** or **5**)
  - The numerical workload of each element is identical
  - The mesh elements are numbered from 0 to n-1

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- Two possible solutions:

(A) 17=5+5+5+2 or 5=2+2+1+0 (B) 17=5+4+4+4 or 5=2+1+1+1

#mesh elements per subdomain

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- Two possible solutions: (A) 17=5+5+5+2 or 5=2+2+1+0
  - (B) 17=5+4+4+4 or 5=2+1+1+1
- Output should be like (with B)

I am process 1 out of 4, responsible for the4 elements with indexes5 ... 8I am process 0 out of 4, responsible for the5 elements with indexes0 ... 4I am process 3 out of 4, responsible for the4 elements with indexes13 ... 16I am process 2 out of 4, responsible for the4 elements with indexes9 ... 12

#mesh elements per subdomain

Or -1 if 0 elements

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  - or

 $\sim$ 

Exercise

- F\_30/Ch1/first-dd-**a**\_30.f90 and F\_30/Ch1/first-dd-**b**\_30.f90 Python PY/Ch1/first-dd-a\_30.py and PY/Ch1/first-dd-b\_30.py
- Test both programs with 4 processes and 9, 8, 7, ... 1 elements

#mesh elements per subdomain

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 $\sim$ 

Exercise

or

or

I am process 1 out of 4, responsible for the 4 elements with indexes 5... 8 I am process 0 out of 4, responsible for the 5 elements with indexes 0... 4

I am process 3 out of 4, responsible for the 4 elements with indexes 13 .. 16

I am process 2 out of 4, responsible for the 4 elements with indexes 9..12 In MPI/tasks/...

> Use: C/Ch1/first-dd-a.c С Fortran Python PY/Ch1/first-dd-a\_30.py

and C/Ch1/first-dd-b.c F\_30/Ch1/first-dd-**a**\_30.f90 and F\_30/Ch1/first-dd-**b**\_30.f90 and PY/Ch1/first-dd-b\_30.py

Test both programs with 4 processes and 9, 8, 7, ... 1 elements Which algorithm would you prefer, and why? Which are the major principles of A and B?

#mesh elements per subdomain

Or -1 if 0 elements
# **Collective Communications**

- Collective communication routines are higher level routines.
- Several processes are involved at a time.
- May allow optimized internal implementations, e.g., tree based algorithms.
- Can be built out of point-to-point communications.

# **Broadcast**

• A one-to-many communication.



### **Reduction Operations**

• Combine data from several processes to produce a single result.



### **Barriers**



• Synchronize processes.

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• Synchronize processes.









calculation on	time for computation	time for <u>serial</u> I/O
1 core	64 min	1 min
= sequentiel	= 98.5 % of total time	= 1.5 % of total time
64 cores	1 min	1 min
= in parallel	= 50 % of total time	= <b>50 %</b> of total time

Table: example with serial I/O



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• Definition:T(p,N) = time to solve problem of total size N on p processors• Parallel speedup:S(p,N) = T(1,N) / T(p,N)<br/>compute same problem with more processorsThree different ways of<br/>reporting the success• Parallel Efficiency:E(p,N) = S(p,N) / p

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 Scaleup: Sc(p,N) = N / n with T(1,n) = T(p,N) compute larger problem with more processors in same time

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- Problems:
  - Absolute MFLOPS rate / hardware peak performance?
  - Super-scalar speedup: S(p,N)>p, e.g., due to cache<sup>\*</sup>) usage for large p:
    - T(1,N) may be based on a huge number of N data elements in the memory in the one process, whereas
    - T(p,N) may be based on *cache based execution* due to only N/p data elements per process
  - S(p,N) close to **p** or far less?  $\rightarrow$  see Amdahl's Law on next slide

#### Amdahl's Law

 $T(p,N) = f \cdot T(1,N) + (1-f) \cdot T(1,N) / p$ f ... sequential part of code that can not be done in parallel S(p,N) = T(1,N) / T(p,N) = 1 / (f + (1-f) / p)For p —> infinity, speedup is limited by S(p,N) < 1 / f



S(p,N) = p (ideal speedup)
 f=0.1% => S(p,N) < 1000</li>
 f= 1% => S(p,N) < 100</li>
 f= 5% => S(p,N) < 20</li>
 f= 10% => S(p,N) < 10</li>

#### Amdahl's Law (double-logarithmic)

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# Quiz on Chapter 1 – Overview

Two developers report about their limited success when parallelizing an application:

- A. "My application is now running in parallel with 1000 MPI processes and my major limiting factor for scaling is
  - that I need about 90% of the whole compute time for MPI communication."
- B. "My application is now running in parallel with 1000 MPI processes and my major limiting factor for scaling is
  - that I could not parallelize about 10% of the execution time of my sequential program."

What are your answers for

- In your opinion, who was **more successful, A** or **B**, or both **almost equally**?
- Can you calculate an estimate for the parallel efficiency of the parallel run reported by A and B?