Parallel programming / computation

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Lecture 1 **MPI Overview**

- 1. MPI Overview
	- **one program on several processors**
	- **work and data distribution**

- 2. Process model and language bindings
	- **starting several MPI processes**

MPI_Init() MPI_Comm_rank()

- 3. Messages and point-to-point communication
	- **the MPI processes can communicate**
- 4. Nonblocking communication
	- **to avoid idle time, deadlocks and serializations**

- 5. The New Fortran Module mpi_f08
- 6. Collective communication
	- **(1) e.g., broadcast**
	- **(2) e.g., nonblocking collectives, neighborhood communic.**
- 7. Error handling
	- **error handler, codes, and classes**

- 8. Groups & Communicators, Environmental Management
	- **(1) MPI_Comm_split, intra- & inter-communicators**
	- **(2) Re-numbering on a cluster, collective communication on inter-communicators, info object, naming & attribute caching, implementation information, Sessions Model**
- 9. Virtual topologies – **(1) A multi-dimensional process naming scheme** – **(2) Neighborhood communication + MPI_BOTTOM**

Handout is sorted by

– **(3) Optimization through reordering**

content ... <u>*s* ... whereas **course** is</u> sorted by **beginners / intermediate / advanced**

- 10. One-sided Communication
	- **Windows, remote memory access (RMA)**
	- **Synchronization**

- 11. Shared Memory One-sided Communication
	- **(1) MPI_Comm_split_type & MPI_Win_allocate_shared Hybrid MPI and MPI shared memory programming**
	- **(2) MPI memory models and synchronization rules**
- 12. Derived datatypes

- **(1) transfer any combination of typed data**
- **(2) advanced features, alignment, resizing**
- 13. Parallel File I/O
	- **(1) Writing and reading a file in parallel**
	- **(2) Fileviews**
	- **(3) Shared Filepointers, Collective I/O …**
- 14. MPI and Threads
	- **e.g., hybrid MPI and OpenMP, partitioned point-to-point communication**

- 15. Probe, Persistent Requests, Cancel
- 16. Process Creation and Management
	- **Spawning additional processes**
	- **Singleton MPI_INIT**
	- **Connecting two independent sets of MPI processes**
- 17. Other MPI features [1, 2, 13.1-3, 15, 16-18, 19.3, A, A.2, B]
- 18. Best practice
	- **Parallelization strategies (e.g. Foster's Design Methodology)**
	- **Performance considerations**
	- **Pitfalls and progress / weak local**
- 19. Heat example

Summary

Appendix

MPI Outline

Information about MPI

- **MPI: A Message-Passing Interface Standard,** Version 4.0 (June 9, 2021) (pdf & printed hardcover book [MPI-3.1 only] \rightarrow online via www.mpi-forum.org)
- Marc Snir and William Gropp et al.: **MPI: The Complete Reference**, 1998. *(outdated)*
- William Gropp, Ewing Lusk and Anthony Skjellum: **Using MPI: Portable Parallel Programming With the Message-Passing Interface.** MIT Press, 3rd edition, Nov. 2014 *(336 pages, ISBN* 9780262527392*),* and William Gropp, Torsten Hoefler, Rajeev Thakur and Ewing Lusk: **Using Advanced MPI: Modern Features of the Message-Passing Interface.** MIT Press, Nov. 2014 *(392 pages, ISBN* 9780262527637*).*
- Peter S. Pacheco: **Parallel Programming with MPI**. Morgan Kaufmann Publishers, 1997 *(very good introduction, can be used as accompanying text for MPI lectures).*
- Neil MacDonald, Elspeth Minty, Joel Malard, Tim Harding, Simon Brown, Mario Antonioletti: **Parallel Programming with MPI**. Historical MPI course notes from EPCC. http://www.archer.ac.uk/training/course-material/2014/10/MPI_UCL/Notes/MPP-notes.pdf
- All MPI standard documents and errata via **www.mpi-forum.org**
- http://en.wikipedia.org/wiki/Message Passing Interface (English) http://de.wikipedia.org/wiki/Message_Passing_Interface (German)
- **Tools:** see VI-HPS (Virtual Institute High Productivity Supercomputing) https://www.vi-hps.org/ Tools Guide: https://www.vi-hps.org/cms/upload/material/general/ToolsGuide.pdf & training events
- **Python:** See MPI for Python (mpi4py.github.io), and MPI for Python documentation (mpi4py.readthedocs.io), and the Reference (mpi4py.readthedocs.io/en/stable/reference.html)

The Message-Passing Programming Paradigm

• **Sequential Programming Paradigm**

The Message-Passing Programming Paradigm

• **Sequential Programming Paradigm**

• **Message-Passing Programming Paradigm**

Analogy: Electric Installations in Parallel

- MPI sub-program = work of one electrician on one floor
- MPI process on a dedicated hardware $=$ the electrician
- data $=$ the electric installation
- MPI communication = real communication to guarantee that the wires are coming at the same position through the floor

shared memory

Socket/CPU

memory interface

UMA (uniform memory access) SMP (symmetric multi-processing) All cores connected to all memory banks with same speed

Parallel execution streams on each

core, e.g., $x[$ 0 ... 999] = ... on 1st core $x[1000...1999] = ...$ on 2^{nd} core $x[2000... 2999] = ...$ on 3rd core

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Node

 hyper-transport ccNUMA (cache-coherent non-uniform

memory access)

 \rightarrow Shared memory programming is possible **!! #CPUs x memory bandwidth !!**

Performance problems:

- Each **parallel execution stream** should mainly access the memory of **its** CPU \rightarrow **First-touch** strategy is needed to minimize remote memory access
- Threads should be **pinned** to the physical sockets

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Shared memory programming with OpenMP

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Shared memory programming with OpenMP

Node || Node ||Node node-interconnect distributed memory

Cluster

→ node-interconnect

NUMA (non-uniform memory access)

!! fast access only on its own memory **!! Many programming options:**

- Shared memory / symmetric multiprocessing inside of each node
- distributed memory parallelization on the node interconnect
- **Or simply one MPI process on each core**

shared memory

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…

memory interface

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distributed memory

Cluster

→ node-interconnect

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- Shared memory / symmetric multiprocessing inside of each node
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- **Or simply one MPI process on each core**

Shared memory programming with OpenMP

MPI works everywhere

The Message-Passing Programming Paradigm

- Each processor in a message passing program runs a *sub-program:*
	- written in a conventional sequential language, e.g., C, Fortran, or Python
	- typically the same on each processor (SPMD),
	- the variables of each sub-program have
		- **the same name**
		- **but different locations (distributed memory) and different data!**
		- **i.e., all variables are private**
	- communicate via special send & receive routines (*message passing*)

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Data and Work Distribution

- the value of *myrank* is returned by special library routine
- the system of *size* processes is started by special MPI initialization program (mpirun or mpiexec)
- all distribution decisions are based on *myrank*
- i.e., which process works on which data

What is SPMD?

- **S**ingle **P**rogram, **M**ultiple **D**ata
- Same (sub-)program runs on each processor
- MPI allows also MPMD, i.e., **Multiple** Program, ...
- but some vendors may be restricted to SPMD
- MPMD can be emulated with SPMD

Emulation of Multiple Program (MPMD), Example

```
• main(int argc, char **argv)
    {
           if (myrank < .... /* process should run the ocean model */)
           {
                     ocean( /* arguments */ );
          }else{
                     weather( /* arguments */ );
          }
    }
```
- PROGRAM IF (myrank $<$...) THEN !! process should run the ocean model CALL ocean (some arguments) ELSE CALL weather (some arguments) ENDIF END
- if (myrank \lt ): # process should run the ocean model ocean(…) else: weather(…)

Emulation of Multiple Program (MPMD), Example

```
main(int argc, char **argv)
{
       if (myrank \lt .... /* process should run the ocean model */)
       {
                 ocean( /* arguments */ );
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```
• PROGRAM IF (myrank $< ...$) THEN $\;$!! process should run the ocean model CALL ocean (some arguments) ELSE CALL weather (some arguments) ENDIF END

first-example.c


```
#include <stdio.h>
first-example.c
#include <mpi.h>
int main(int argc, char *argv[])
{
```
MPI_Init(&argc, &argv);

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}

MPI course \rightarrow Chap. 1 Overview

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MPI course \rightarrow Chap. 1 Overview

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Exercise 1 – Solution + Questions

mpif90 first-example_30.f90 mpirun **-**np 6 ./a.out Enter the number of elements (n): 100 I am process θ out of θ handling the 0th part of n= 100 elements, result= θ .00 I am process 1 out of 6 handling the 1th part of n= 100 elements, result= 100.00 I am process 2 out of 6 handling the 2th part of n= 100 elements, result= 200.00 I am process 3 out of 6 handling the 3th part of n= 100 elements, result= 300.00 I am process 4 out of 6 handling the 4th part of n= 100 elements, result= 400.00 I am process 5 out of 6 handling the 5th part of n= 100 elements, result= 500.00 I'm proc 0: My own result is 0.00 I'm proc 0: received result of process 1 is 100.00 I'm proc 0: received result of process 2 is 200.00 I'm proc 0: received result of process 3 is 300.00 I'm proc 0: received result of process 4 is 400.00 I'm proc 0: received result of process 5 is 500.00

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Normally, you'll never see this perfect output !

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Exercise 1 – Solution + Answers

Exercise 1 – Solution + Answers

The output from different processes can be intermixed in any sequence! Most MPI libraries try to not intersect output lines \odot

Access

- A sub-program needs to be connected to a message passing system
- A message passing system is similar to:
	- mail box
	- phone line
	- fax machine
	- etc.
- MPI:
	- sub-program must be linked with an MPI library
	- sub-program must use include file of this MPI library
	- the total program (i.e., all sub-programs of the program) must be started with the MPI startup tool

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Messages

- Messages are packets of data moving between sub-programs
- Necessary information for the message passing system:
	-
	-
	-
	-
- sending process $-$ receiving process $\left\{\right.$ i.e., the ranks
- source location destination location
- $-$ source data type $-$ destination data type
- source data size destination buffer size

Messages

- Messages are packets of data moving between sub-programs
- Necessary information for the message passing system:

Addressing

- Messages need to have addresses to be sent to.
- Addresses are similar to:
	- mail addresses
	- phone number
	- fax number
	- etc.
- MPI: addresses are ranks of the MPI processes (sub-programs)

Receiving

• All messages must be received.

Point-to-Point Communication

- Simplest form of message passing.
- One process sends a message to another.
- Different types of point-to-point communication:
	- synchronous send
	- buffered = asynchronous send

Synchronous Sends

- The sender gets an information that the message is received.
- Analogue to the *beep* or *okay-sheet* of a fax.

Buffered = Asynchronous Sends

• Only know when the message has left.

Blocking Operations

- Operations are activities, such as
	- sending (a message)
	- receiving (a message)
- Some operations may **block** until another process acts:
	- synchronous send operation **blocks until** receive is posted;
	- receive operation **blocks until** message was sent.
- Relates to the completion of an operation.
- Blocking subroutine returns only when the operation has completed.

Nonblocking Operations

Nonblocking operations consist of:

- A nonblocking procedure call: it returns immediately and allows the sub-program to perform other work
- At some later time the sub-program must *test* or *wait* for the completion of the nonblocking operation

Non-Blocking Operations (cont'd)

- All nonblocking procedures must have a matching wait (or test) procedure. (Some system or application resources can be freed only when the nonblocking operation is completed.)
- A nonblocking procedure immediately followed by a matching wait is equivalent to a blocking procedure.
- Nonblocking procedures are not the same as sequential subroutine calls:
	- the operation may continue while the application executes the next statements!

Interrupt: Example & Exercise 2

- Before we further go through the MPI chapter overview on
	- Collective Communication
	- Parallel file I/O
- Lets look at halo communication
- plus a short exercise 2

Example: Domain decomposition – serial

• $x_{new} (i,j) = f (x_{old}(i-1,j), x_{old} (i,j), x_{old} (i+1,j), x_{old} (i,j-1), x_{old} (i,j+1))$

Example: Domain decomposition – parallel

 $x_{\text{new}}(i,j) = f(x_{\text{old}}(i-1,j), x_{\text{old}}(i,j), x_{\text{old}}(i+1,j), x_{\text{old}}(i,j-1), x_{\text{old}}(i,j+1))$

Example: Domain decomposition – parallel

 $X_{\text{new}}(i,j) = f(X_{\text{old}}(i-1,j), X_{\text{old}}(i,j), X_{\text{old}}(i+1,j), X_{\text{old}}(i,j-1), X_{\text{old}}(i,j+1)))$

Communication: Send inner data \Rightarrow into halo storage

Communication: Send inner data \Rightarrow into halo storage

parallel code:

Communication: Send inner data \Rightarrow into halo storage

parallel code:

 \Box

Example code

ib_global = 0; ie_global=n-1; // global xold, xnew: arrays with n elements and indexes 0 .. n-1

```
for(….) / e.g. timesteps
{
```

```
numerical_func( xold, xnew, ib_global, ie_global);
 tmp=xold; xold=xnew; xnew=tmp; // exchanging role of xold and xnew
}
```
 \Box

Example code

ib_global = 0; ie_global=n-1; // global xold, xnew: arrays with n elements and indexes 0 .. n-1

Goal: Divide a given amount of mesh elements in one dimension into subdomains

- Given: The number of processes: num_procs (e.g., **4**, i.e., 4 subdomains)
	- The number of mesh elements: n (e.g., **17** *or* **5**)
	- The numerical workload of each element is identical
	- The mesh elements are numbered from **0** to **n-1**

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• **Two possible solutions: (A) 17=5+5+5+2** *or* **5=2+2+1+0 (B) 17=5+4+4+4** *or* **5=2+1+1+1**

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	- or F_30/Ch1/first-dd-**a**_30.f90 and F_30/Ch1/first-dd-**b**_30.f90 **Fortran** or **Python PY/Ch1/first-dd-a_30.py** and PY/Ch1/first-dd-b_30.py

Exercise 2

-
- Test both programs with 4 processes and 9, 8, 7, … 1 elements

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• Test both programs with 4 processes and 9, 8, 7, … 1 elements Which algorithm would you prefer, and why? Which are the major principles of A and B?
Collective Communications

- Collective communication routines are higher level routines.
- Several processes are involved at a time.
- May allow optimized internal implementations, e.g., tree based algorithms.
- Can be built out of point-to-point communications.

Broadcast

• A one-to-many communication.

Reduction Operations

• Combine data from several processes to produce a single result.

Barriers

• Synchronize processes.

Barriers

• Synchronize processes.

Table: example with serial I/O

• Definition: T(p,N) = **time** to solve **problem of total size N** on **p processors** • Parallel speedup: $S(p,N) = T(1,N) / T(p,N)$ compute **same problem** with more processors in **shorter time** • Parallel Efficiency: $E(p,N) = S(p,N)/p$ Three different ways of reporting the success

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- Problems:
	- Absolute MFLOPS rate **/** hardware peak performance?
	- Super-scalar speedup: $S(p,N)$ >p, e.g., due to cache^{*)} usage for large p:
		- **T(1,N) may be based on a huge number of N data elements in the memory in the one process, whereas**
		- **T(p,N) may be based on** *cache based execution* **due to only N/p data elements per process**
	- $S(p,N)$ close to **p** or far less? \rightarrow see Amdahl's Law on next slide

Amdahl's Law

 $T(p,N) = f \cdot T(1,N) + (1-f) \cdot T(1,N) / p$ f ... sequential part of code that can not be done in parallel $S(p,N) = T(1,N) / T(p,N) = 1 / (f + (1-f) / p)$ For $p \rightarrow$ infinity, speedup is limited by $S(p,N) < 1/f$

S(p,N) = p (ideal speedup) \rightarrow f=0.1% => S(p,N) < 1000 $f= 1\% \Rightarrow S(p,N) < 100$ $f= 5\% \Rightarrow S(p,N) < 20$ \rightarrow f= 10% => S(p,N) < 10

Amdahl's Law (double-logarithmic)

 $T(p,N) = f \cdot T(1,N) + (1-f) \cdot T(1,N) / p$ f ... sequential part of code that can not be done in parallel $S(p,N) = T(1,N) / T(p,N) = 1 / (f + (1-f) / p)$ For $p \rightarrow$ infinity, speedup is limited by $S(p,N) < 1/f$

S(p,N) = p (ideal speedup) \rightarrow f=0.1% => S(p,N) < 1000 \rightarrow f= 1% => S(p,N) < 100 $f= 5\% \Rightarrow S(p,N) < 20$ \rightarrow f= 10% => S(p,N) < 10

Quiz on Chapter 1 – Overview

Two developers report about their limited success when parallelizing an application:

- A. "My application is now running in parallel with 1000 MPI processes and my major limiting factor for scaling is
	- that I need about 90% of the whole compute time for MPI communication."
- B. "My application is now running in parallel with 1000 MPI processes and my major limiting factor for scaling is
	- that I could not parallelize about 10% of the execution time of my sequential program."

What are your answers for

- In your opinion, who was **more successful, A** or **B**, or both **almost equally**?
- Can you calculate an estimate for the parallel efficiency of the parallel run reported by A and B?