### Lecture 11 Hash Tables

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## The Search Problem

- Unsorted list
  - O(N)
- Sorted list
  - O(logN) using arrays (i.e., binary search)
  - O(N) using linked lists
- Binary Search tree
  - O(logN) (i.e., balanced tree)
  - O(N) (i.e., unbalanced tree)
- Can we do better than this?
  - Direct Addressing
  - Hashing

## **Direct Addressing**

- Assumptions:
  - Key values are **distinct**
  - Each key is drawn from a universe U =  $\{0, 1, \ldots, n 1\}$

- Idea:
  - Store the items in an array, indexed by keys

## Direct Addressing (cont'd)

- **Direct-address table** representation:
  - An array T[0 . . . n 1]
  - Each **slot**, or position, in T corresponds to a key in U

For an element x with key k, a pointer to x will be placed in location T[k]

 If there are no elements with key k in the set, T[k] is empty, represented by NIL



Search, insert, delete in O(1) time!

## Direct Addressing (cont'd)

Example 1: Suppose that the are integers from 1 to 100 and that there are about 100 records.

Create an array A of 100 items and stored the record whose key is equal to **i** in in **A[i]**.



|K| = |U||K|: # elements in K

|U|: # elements in U

## Direct Addressing (cont'd)

Example 2: Suppose that the keys are 9-digit social security numbers (SSN)

Although we could use the same idea, it would be very inefficient (i.e., use an array of 1 billion size to store 100 records)



|K| << |U|

# Hashing

#### Idea:

- Use a function **h** to compute the slot for each key
- Store the element in slot h(k)
- A hash function h transforms a key into an index in a hash table T[0...m-1]:

$$h: U \rightarrow \{0, 1, \ldots, m-1\}$$

• We say that k hashes to slot h(k)

# Hashing (cont'd)



 $h: U \rightarrow \{0, 1, \ldots, m-1\}$ 

hash table size: m

# Hashing (cont'd)

Example 2: Suppose that the keys are 9-digit social security numbers (SSN)

### Possible hash function

*h*(*ssn*) = *sss* mod 100 (last 2 digits of ssn) e.g., if *ssn* = 10123411 then *h*(10123411) = 11)

### Advantages of Hashing

Reduce the range of array indices handled:
 m instead of |U|
 where m is the hash table size: T[0, ..., m-1]

• Storage is reduced.

• O(1) search time (i.e., under assumptions).

### Collisions

Collisions occur when  $h(k_i)=h(k_i)$ ,  $i \neq j$ 



# Collisions (cont'd)

- For a given set K of keys:
  - If |K| ≤ m, collisions may or may not happen,
     depending on the hash function!
  - If |K| > m, collisions will definitely happen (i.e., there must be at least two keys that have the same hash value)
- Avoiding collisions completely might not be easy.

# Handling Collisions

• We will discuss two main methods:

### (1) Chaining

### (2) Open addressing

- Linear probing
- Quadratic probing
- Double hashing

# Chaining

#### • Idea:

Put all elements that hash to the same slot into a linked list



 Slot j contains a pointer to the head of the list of all elements that hash to j

# Chaining (cont'd)

- How to choose the size of the hash table **m**?
  - Small enough to avoid wasting space.
  - Large enough to avoid many collisions and keep linked-lists short.
  - Typically 1/5 or 1/10 of the total number of elements.
- Should we use sorted or unsorted linked lists?
  - Unsorted
    - Insert is fast
    - Can easily remove the most recently inserted elements

### Hash Table Operations

- Search
- Insert
- Delete

## Searching in Hash Tables

*Alg.:* CHAINED-HASH-SEARCH(T, k)

search for an element with key k in list T[h(k)]

 Running time <u>depends</u> on the length of the list of elements in slot h(k)

### Insertion in Hash Tables

Alg.: CHAINED-HASH-INSERT(T, x)

insert x at the head of list T[h(key[x])]

T[h(key[x])] takes O(1) time; insert will take O(1) time overall since lists are unsorted.

• <u>Note:</u> if no duplicates are allowed, It would take extra time to check if item was already inserted.

### **Deletion in Hash Tables**

*Alg.:* CHAINED-HASH-DELETE(T, x) delete x from the list T[h(key[x])]

- T[h(key[x])] takes O(1) time.
- Finding the item <u>depends</u> on the length of the list of elements in slot h(key[x])

### Analysis of Hashing with Chaining: Worst Case

 How long does it take to search for an element with a given key?

- Worst case:
  - All n keys hash to the same slot
- then O(n) plus time to compute the hash function



### Analysis of Hashing with Chaining: Average Case

- It depends on how well the hash function distributes the n keys among the m slots
- Under the following assumptions:
   (1) n = O(m)

(2) any given element is **equally likely** to hash into any of the **m** slots (i.e., simple uniform hashing property)

then  $\rightarrow$  O(1) time plus time to compute the hash function



## **Properties of Good Hash Functions**

### Good hash function properties

- (1) Easy to compute
- (2) Approximates a random function
  - i.e., for every input, every output is equally likely.
- (3) Minimizes the chance that similar keys hash to the same slot

i.e., strings such as pt and pts should hash to different slot.

#### • We will discuss two methods:

- Division method
- Multiplication method

# The Division Method

#### • Idea:

– Map a key k into one of the m slots by taking the remainder of k divided by m h(k) = k mod m

#### Advantage:

- fast, requires only one operation

### **Disadvantage**:

- Certain values of m are bad (i.e., collisions), e.g.,
  - power of 2
  - non-prime numbers

# Example

_			m	m
•	If $m = 2^p$ then $h(k)$ is just the least		97	100
-	$\Pi \Pi = \Sigma^{\prime}, \Pi C \Pi \Pi (K) IS JUST THE TEAST$	16838	57	38
	significant n hits of k	5758	35	58
	Significant p bits of K	10113	25	13
	$-n-1 \rightarrow m-2$	21051	55 11	10 51
	$-p-1 \rightarrow m-2$	5627	1	27
	$\rightarrow h(k) = (0, 1)$ locat cignificant 1 bit of k	23010	21	10
	$\rightarrow n(\kappa) - \{0, 1\}$ , least significant 1 bit of $\kappa$	7419	47	19
	$-n-2 \rightarrow m-1$	16212	13	12
	$-p-z \rightarrow m-4$	4086	12	86
	$\rightarrow h(k) - (0, 1, 2, 3)$ loget significant 2 hits of k	2749	33	49
	$\rightarrow n(\kappa) - \{0, 1, 2, 3\}$ , least significant 2 bits of $\kappa$	12767	60	67
_		9084	63	84
•	Choose <b>m</b> to be a prime, not close to a	12060	32	60 05
		32223	21 83	20 43
	power of 2	25089	63	89
		21183	37	83
	Column 2: k mod 97	25137	14	37
		25566	55	<b>10</b> 38 58 13 15 51 27 10 19 12 86 49 67 84 60 25 43 89 83 37 66 66 78 95 11 67
	• Column 3: k mod 100	26966	0	66
		4978	31	78
		20495	28	95
		10311	29 10	11 67
		11201	10	10

## The Multiplication Method

#### Idea:

- (1) Multiply key k by a constant A, where 0 < A < 1
- (2) Extract the fractional part of kA
- (3) Multiply the fractional part by m
- (4) Truncate the result

$$h(k) = \lfloor m(kA - \lfloor kA \rfloor) \rfloor = \lfloor m (k A \mod 1) \rfloor$$
  
e.g.,  $\lfloor 12.3 \rfloor = 12$  fractional part of kA = kA

- **Disadvantage:** Slower than division method
- Advantage: Value of m is not critical

- | kA |

### **Example – Multiplication Method**

Suppose k=6, A=0.3, m=32

(1) 
$$k \times A = 1.8$$

(2) fractional part:  $1.8 - \lfloor 1.8 \rfloor = 0.8$ 

(3) m x  $0.8 = 32 \times 0.8 = 25.6$ 

(4) 
$$\lfloor 25.6 \rfloor = 25$$
 h(6)=25

# **Open Addressing**

- Idea: store the keys in the table itself
- No need to use linked lists anymore
- Basic idea:
  - <u>Insertion</u>: if a slot is full, try another one, until you find an empty one.
  - <u>Search</u>: follow the same probe sequence.
  - <u>Deletion</u>: need to be careful!
- Search time depends on the length of probe sequences!





### Generalize hash function notation:

A hash function contains two arguments now:
 (i) key value, and (ii) probe number
 e.g., ins

h(k,p), p=0,1,...,m-1

- Probe sequence:
   <h(k,0), h(k,1), h(k,2), .... >
- Example:

Probe sequence: <h(14,0), h(14,1), h(14,2)>=<1, 5, 9>



### Generalize hash function notation:

#### – Probe sequence must be a permutation of <0,1,...,m-1>

#### – There are **m!** possible permutations



Probe sequence: <h(14,0), h(14,1), h(14,2)>=<1, 5, 9>

### **Common Open Addressing Methods**

- Linear probing
- Quadratic probing
- Double hashing
- None of these methods can generate more than m<sup>2</sup> different probe sequences!

# Linear probing: Inserting a key

 Idea: when there is a collision, check the <u>next</u> available position in the table:

> $h(k,i) = (h_1(k) + i) \mod m$ i=0,1,2,...

- i=0: first slot probed: h<sub>1</sub>(k)
- i=1: second slot probed:  $h_1(k) + 1$
- i=2: third slot probed:  $h_1(k)+2$ , and so on

probe sequence:  $< h_1(k), h_1(k)+1, h_1(k)+2, ... >$ 

How many probe sequences can linear probing generate?

m probe sequences maximum

wrap around

# Linear probing: Searching for a key

- Given a key, generate a probe sequence using the same procedure.
- Three cases:
  - (1) Position in table is occupied with an element of equal key → FOUND
  - (2) Position in table occupied with a different element  $\rightarrow$  KEEP SEARCHING

(3) Position in table is empty  $\rightarrow$  NOT FOUND



# Linear probing: Searching for a key

- Running time depends on the length of the probe sequences.
- Need to keep probe sequences short to ensure fast search.



# Linear probing: Deleting a key

- First, find the slot containing the key to be deleted.
- Can we just mark the slot as empty?
  - It would be impossible to retrieve keys inserted after that slot was occupied!
- Solution
  - "Mark" the slot with a sentinel value DELETED
- The deleted slot can later be used for insertion.

	0	
)	1	79
	2	1 kons
	3	
	4	69
	5	98
	6	
	7	72
	8	
	9	14
	10	
	11	50
n	12	2.39

# Primary Clustering Problem

- Long chunks of occupied slots are created.
- As a result, some slots become more likely than others.
- Probe sequences increase in length. ⇒ search time increases!!

initially, all slots have probability 1/m



## Quadratic probing

$$h(k, i) = (h'(k) + c_1 i + c_2 i^2) \mod m$$
, where  $h': U - - > (0, 1, ..., m - 1)$ 

i=0,1,2,...

- Clustering is less serious but still a problem (secondary clustering)
- How many probe sequences can quadratic probing generate?

m -- the initial position determines probe sequence

# **Double Hashing**

- (1) Use one hash function to determine the first slot.
  (2) Use a second hash function to determine the increment for the probe sequence:
  h(k,i) = (h<sub>1</sub>(k) + i h<sub>2</sub>(k)) mod m, i=0,1,...
- Initial probe: h<sub>1</sub>(k)
- Second probe is offset by  $h_2(k) \mod m$ , so on ...
- Advantage: handles clustering better
- Disadvantage: more time consuming
- How many probe sequences can double hashing generate?

## Double Hashing: Example

 $h_1(k) = k \mod 13$ ()  $h_2(k) = 1 + (k \mod 11)$  $h(k,i) = (h_1(k) + i h_2(k)) \mod 13$ • Insert key 14:  $i=0: h(14,0) = h_1(14) = 14 \mod 13 = 1$  $i=1: h(14,1) = (h_1(14) + h_2(14)) \mod 13$  $= (1 + 4) \mod 13 = 5$ i=2:  $h(14,2) = (h_1(14) + 2 h_2(14)) \mod 13$  $= (1 + 8) \mod 13 = 9$